

# Path by path uniqueness of stochastic differential equations

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# Table of Content

- 1 Motivation & Definitions
- 2 Strategy of the proof
- 3 Proof of the Approximation Theorem
- 4 Main result

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## Stochastic Differential Equations in infinite dimensions

On a fixed probability space  $(\Omega, \mathcal{F}, (\mathcal{F}_t)_{t \in [0, T]}, \mathbb{P})$  we consider the stochastic differential equation

$$dX_t = -AX_t dt + f(t, X_t) dt + dW_t, \quad X_0 = 0 \quad (\text{SDE}).$$

- $W$  is a cylindrical **Brownian motion**,
- $f: [0, T] \times H \rightarrow H$  is a **bounded** Borel function,
- $A: D(A) \rightarrow H$  is positive definite, self-adjoint, linear,  $A^{-1}$  is trace class.

$$Ae_n = \lambda_n e_n, \quad \text{with } \lambda_n > 0 \text{ and}$$

$$\sum_{n \in \mathbb{N}} \lambda_n^{-1} < \infty.$$

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## Solution

We say a **stochastic process**  $(X_t)_{t \in [0, T]}$  is a **solution** to

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if  $\mathbb{P}$ -a.s. for all  $t \in [0, T]$  we have

$$X_t = \int_0^t e^{-(t-s)A} f(s, X_s) ds + \underbrace{\int_0^t e^{-(t-s)A} dW_s}_{\text{stochastic integral}}. \quad (\text{IE})$$

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### Pathwise Uniqueness

Let  $(X_t)_{t \in [0, T]}$  and  $(Y_t)_{t \in [0, T]}$  be two solutions then  $\mathbb{P}$ -a.s.  $X_t = Y_t$  for all  $t \in [0, T]$ , i.e.

$$\exists \Omega_0 \subseteq \Omega: \mathbb{P}[\Omega_0] = 1: \forall (\omega, t) \in \Omega_0 \times [0, T]: X_t(\omega) = Y_t(\omega).$$

However,  $\Omega_0$ , a priori, **depends** on both  $X$  and  $Y$ .

**Question:** Can  $\Omega_0$  be chosen **independently** of  $X$  and  $Y$ ?

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### Path-by-Path Uniqueness

We first plug in an  $\omega \in \Omega$  into the corresponding integral equation of the mild form of (SDE)

$$x_t = \int_0^t e^{-(t-s)A} f(s, x_s) \, ds + Z_t^A(\omega). \quad (\text{IE}_\omega)$$

**Aim:** For **fixed**  $\omega \in \Omega$ , find a **unique** continuous **function**  $x: [0, T] \rightarrow H$  satisfying the equation above.

Uniqueness for ODEs in integral form perturbed by an Ornstein–Uhlenbeck **path**  $Z^A(\omega)$ .

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## Path-by-Path Uniqueness

### Definition

Fix  $\omega \in \Omega$ . Denote by  $\mathcal{S}(\omega)$  the set of all **functions**  $x$  for which

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holds.

### Definition (Path-by-Path Uniqueness)

We say (SDE) exhibits **path-by-path uniqueness** if there exists a measurable set  $\Omega_0 \subseteq \Omega$  with  $\mathbb{P}[\Omega_0] = 1$  such that

$$\#\mathcal{S}(\omega) \leq 1, \quad \forall \omega \in \Omega_0.$$

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## Path-by-Path Uniqueness VS. Pathwise Uniqueness

**Path-by-path uniqueness:** There is a null set  $N \subseteq \Omega$  such that **all solutions** coincide on  $\Omega \setminus N$ . (Uniqueness in the sense of random ODEs).

**Pathwise uniqueness:** Let  $X, Y$  be two solutions. Then  $X = Y$  on  $\Omega \setminus N_{X,Y}$ . The null set **depends** on the solutions!

Path-by-path uniqueness  $\implies$  Pathwise uniqueness

In the case  $H := \mathbb{R}^d$  and  $A = 0$  path-by-path uniqueness was proved by A. Davie in 2007.

The case  $A = -\frac{d^2}{dx^2}$  was proved by O. Butkovsky and L. Mytnik in 2016.

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## The reduced problem

### Strategy of the proof

Let  $(\Omega, \mathcal{F}, (\mathcal{F}_t)_{t \in [0, T]}, \mathbb{P})$  be a probability space such that there exists a **solution**  $(Y_t)_{t \in [0, T]}$  to

$$dY_t = -AY_t dt + f(t, Y_t) dt + dW_t$$

and

$Y_t$  is  $\mathcal{F}_t$ -adapted ( $W_t$  is a cylindrical  $\mathcal{F}_t$ -Brownian motion).

Using **Girsanov's Transformation** we construct an equivalent measure  $\mathbb{Q} \approx \mathbb{P}$  (and a cylindrical Brownian motion  $\tilde{W}$ ) such that  $Y$  is an Ornstein–Uhlenbeck process, i.e.

$$dY_t = -AY_t dt + d\tilde{W}_t$$

under  $\mathbb{Q} \approx \mathbb{P}$ .



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## The reduced problem

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$$u(t) = \int_0^t e^{-(t-s)A} f(s, \underbrace{x_s}_{=u(s)+Y_s(\omega)}) - e^{-(t-s)A} f(s, Y_s(\omega)) \, ds.$$

Since  $Y$  is an Ornstein–Uhlenbeck process under  $\mathbb{Q} \approx \mathbb{P}$  we have reduced our problem to:

### Reduced problem

$$u(t) = \int_0^t e^{-(t-s)A} \left( f(s, u(s) + Z_s^A(\omega)) - f(s, Z_s^A(\omega)) \right) \, ds \stackrel{!!!}{\implies} u \equiv 0$$

for all  $\omega \in \Omega_0 \subseteq \Omega$ ,  $\mathbb{Q}[\Omega_0] = 1$ .

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$$u(t) = \int_0^t e^{-(t-s)A} \left( f(s, u(s) + Z_s^A(\omega)) - f(s, Z_s^A(\omega)) \right) \, ds \stackrel{!!!}{\implies} u \equiv 0$$

for all  $\omega \in \Omega_0 \subseteq \Omega$ ,  $\mathbb{Q}[\Omega_0] = 1$ .

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Fix  $\omega \in \Omega$ . Let  $x$  be a solution to  $(IE_\omega)$ . Set  $u := x - Y(\omega)$ . Then

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## Regularizing Noise

Let  $(X_t, \mathcal{F}_t)$  be a stochastic process.

$$\mathbb{P} \left[ |\varphi_{s,t}(x, y)|_H > \eta |t - s|^h |x - y|_H \mid \mathcal{F}_s \right] \leq C e^{-c\eta^\alpha}. \quad (*)$$

with

$$\varphi_{s,t}(x, y) := \int_s^t f(r, x + X_r(\omega)) - f(r, y + X_r(\omega)) \, dr.$$

### Definition

Given  $Q \subseteq H$ . If  $(*)$  holds for every  $f: [0, 1] \times H \rightarrow Q$  and  $x, y \in Q$  then we say  $X$  is a  **$Q$ -regularizing noise** with index  $h$  and order  $\alpha$ .

A. Davie 2007: Brownian motion in  $\mathbb{R}^d$  is regularizing with  $h = \frac{1}{2}$ ,  $\alpha = 2$

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## Effective Dimension

Let  $Q \subseteq H \subseteq \mathbb{R}^{\mathbb{N}}$ . For every  $m \in \mathbb{N}$  consider  $Q \cap 2^{-m}\mathbb{Z}^{\mathbb{N}}$ .

$$x \in Q \cap 2^{-m}\mathbb{Z}^{\mathbb{N}} \quad \text{then} \quad x = (*, \dots, *, 0, \dots).$$

Let  $d_m \in \mathbb{N} \cup \{+\infty\}$  be the **smallest** number such that  $x_n = 0$  for all  $n \geq d_m$  and all  $x \in Q \cap 2^{-m}\mathbb{Z}^{\mathbb{N}}$ .

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## Properties of $\varphi$

### Properties of $\varphi_{n,k}$

Recall that

$$\varphi_{n,k}(x, \omega) := \int_{k2^{-n}}^{(k+1)2^{-n}} f(t, x + X_t(\omega)) - f(t, X_t(\omega)) dt.$$

If  $X$  is a  $Q$ -regularizing noise and  $\text{ed}(Q)_m \lesssim \ln(m+1)^{1/\gamma}$  we have

$$|\varphi_{n,k}(x)|_H \leq C n^{\frac{1}{\alpha} + \frac{1}{\gamma}} 2^{-hn} (|x|_H + 2^{-2n})$$

and

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## Approximation Theorem

### Theorem (Approximation Theorem)

Let  $h_n: [0, 1] \rightarrow H$  be a sequence of Lipschitz continuous functions converging pointwise to a Lipschitz function  $h$ , then

$$\int_0^1 f(t, X_t(\omega) + h_n(t)) dt \xrightarrow{n \rightarrow \infty} \int_0^1 f(t, X_t(\omega) + h(t)) dt.$$

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If  $f$  were continuous this would follow from Lebesgue's dominated convergence Theorem. We approximate  $f$  by a continuous function  $\bar{f}$ . We are left with proving that

$$\int_0^1 \mathbb{1}_{\{f \neq \bar{f}\}}(t, X_t(\omega) + h(t)) dt \leq \varepsilon$$

uniformly in  $h$ . We can construct  $\bar{f}$  such that  $\{f \neq \bar{f}\}$  is open, so that by exploiting the lower semi-continuity we have

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We rewrite the limit as a telescoping sum

$$\int_0^1 \mathbb{1}_{\{f \neq \bar{f}\}}(t, X_t(\omega) + h_m(t)) dt + \sum_{n=m}^{\infty} \int_0^1 \mathbb{1}_{\{f \neq \bar{f}\}}(t, X_t(\omega) + h_{n+1}(t)) \\ - \mathbb{1}_{\{f \neq \bar{f}\}}(t, X_t(\omega) + h_n(t)) dt,$$

where  $m$  will be chosen later. We split the second integral into the dyadic intervals  $[k2^{-(n+1)}, (k+1)2^{-(n+1)}[$ .

$$\int_0^1 \mathbb{1}_{\{f \neq \bar{f}\}}(t, X_t(\omega) + h_m(t)) dt \\ + \sum_{n=m}^{\infty} \sum_{k=0}^{2^n-1} \varphi_{n+1,k}(\mathbb{1}_{\{f \neq \bar{f}\}}; h_{n+1}(k2^{-(n+1)})) - \varphi_{n+1,k}(\mathbb{1}_{\{f \neq \bar{f}\}}; h_n(k2^{-(n+1)})).$$

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Using the estimate for  $\varphi_{n+1,k}$  this is bounded by

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So that we are left with estimating

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## Main result (in abstract form)

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$$Q := \left\{ x \in \mathbb{R}^{\mathbb{N}} : \sum_{n \in \mathbb{N}} \lambda_n e^{2\lambda_n} |x_n|^2 < C \right\} \\ \cap \left\{ x \in \mathbb{R}^{\mathbb{N}} : |x_n| < \exp(-e^{cn^\gamma}) \right\} \quad \gamma > 2$$

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### Assumptions on the drift $f = (f_n)_{n \in \mathbb{N}}$

We assume that

- $\|f\|_{\infty, A} := \sup_{t \in [0, T], x \in H} \sum_{n \in \mathbb{N}} \lambda_n e^{2\lambda_n} |f_n(t, x)|^2 < \infty$
- $\|f_n\|_{\infty} = \sup_{t \in [0, T], x \in H} |f_n(t, x)| \leq \exp(-e^{n^\gamma})$ , with  $\gamma > 2$

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Theorem (Main result, LW17)

*Under the above assumptions path-by-path uniqueness holds for equation (SDE).*

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Fix an  $\omega \in \Omega$ . Let  $u$  be a function solving

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$$|u((k+1)2^{-n}) - u(k2^{-n})|_H$$

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The reduction via Girsanov transformation only works if our filtered probability space is equipped with a solution (which is  $\mathcal{F}_t$ -measurable).

### Theorem

Given **any** filtered probability space  $(\Omega, \mathcal{F}, (\mathcal{F}_t)_{t \in [0, T]}, \mathbb{P})$  there is a path-by-path unique solution.

On any filtered probability space we can prove that

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